

# Accounting for observer dependence in double-observer distance sampling.

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**Proteus**  
*Knowledge | Results | Data*

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- Non-independent sightings → bias abundance estimates

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- Non-independent sightings → bias abundance estimates
- Previous approaches:
  - Use CDS on sightings by either observer, and MR to adjust  $p.(0)$   
e.g., Borchers et al. 1998, Laake 1999
  - Model  $p_{12}$  as  $\delta p_1 p_2$   
e.g., Buckland et al. 2010

# Conceptual model

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- Define detection probability modelled as:

$$\text{logit}(p_{ij}|y_i, \mathbf{x}_i, z_{ik}) = f_j(\boldsymbol{\beta}_j|y_i, \mathbf{x}_i) + g(\boldsymbol{\alpha}|y_i, \mathbf{x}_i)z_{ik}$$

- $z_{ij}$  = group  $i$  sighted by observer  $j$   
 $\sim \text{Bern}(p_{ij})$
- $y_i$  = distance to group  $i$
- $\mathbf{x}_i$  = other covariates

# Dependence structures

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Full Independence:  $g(\boldsymbol{\alpha}|y_i, \mathbf{x}_i) = 0$

Constant Dependence:  $g(\boldsymbol{\alpha}|y_i, \mathbf{x}_i) = \alpha_0$

Point Independence:  $g(\boldsymbol{\alpha}|y_i, \mathbf{x}_i) = \alpha_1 y_i$

Limiting Independence:  $g(\boldsymbol{\alpha}|y_i, \mathbf{x}_i) = \alpha_0 + \alpha_1 y_i$

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- Line transect surveys conducted along east coast of South Island in 2013

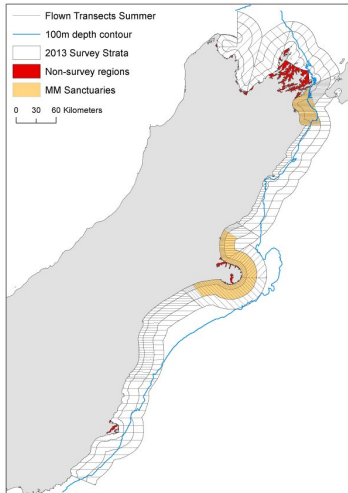
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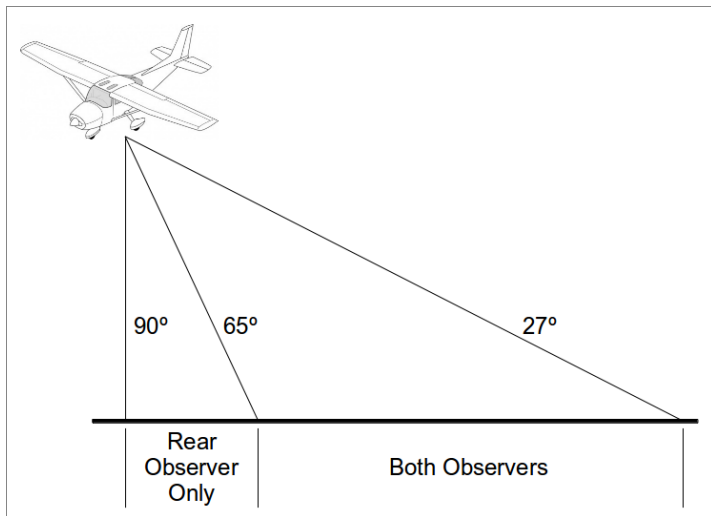
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- Example results: models with quadratic distance and group size effects

Model	$\Delta AIC$	$K$	$-2l$	$\hat{N}_C$	$SE$	$\hat{\alpha}_0$	$\hat{\alpha}_1$ (km)
LI	0.00	6	472.95	967	41	-3.01	18.39
PI	4.05	5	479.01	1,233	118		9.7
FI	21.96	4	498.91	970	36		
C	22.14	5	497.09	1,086	105	0.91	

$\hat{N}_C$  is estimate of available dolphins within survey strip width, and not total abundance.

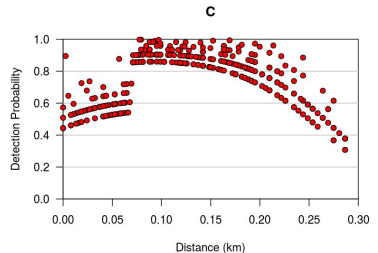
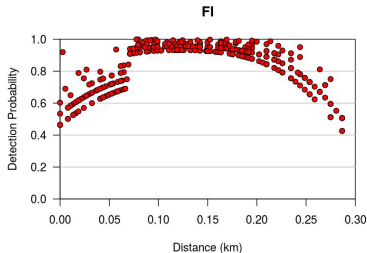
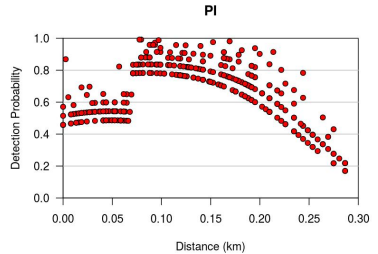
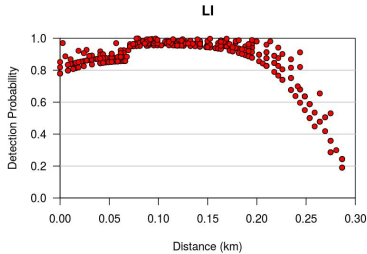
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# Final comments

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- Assumed dependence structure can effect abundance estimates

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- Assumed dependence structure can effect abundance estimates
- Intuitively simple idea

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- Assumed dependence structure can effect abundance estimates
- Intuitively simple idea
- Leads to multinomial cell probabilities

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- Alternative link functions?

# Final comments

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- Extension to  $>2$  observers?

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- Extension to  $>2$  observers?
- Other applications?